

Electrostatic Discharge Cross Talk Attenuation in Protective Meander Lines

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ABSTRACT

It is known that electrostatic discharge (ESD) is one of the frequent causes of integrated circuit failure and loss of spacecraft. However, the danger is not only the pulse itself but also the cross talk from it at the near (NEXT) and far (FEXT) ends. To investigate the possibility of their attenuating by meander line (ML) with a broadside coupling, a coupled microstrip line (MSL) was studied. As a result, the structure with a protected active line appeared to be the most promising. Also, the levels of NEXT and FEXT in it do not exceed 2% and 1.5% of half of the e.m.f. at $s = 1000 \mu\text{m}$, and when $s = 100 \mu\text{m}$ 10% and 3%. In addition to evaluating signal attenuation, N -norms were analyzed as well. The most noteworthy is the nonlinear nature of the change in N_2 depending on s . It is also notable that the proposed protection of the line from cross talk leads to a decrease in N_1 , N_2 , and N_5 . However, N_3 and N_4 increase at the same time.

Index Terms—Coupled lines, cross talk, electrostatic discharge, meander line, protective device

I. INTRODUCTION

Ensuring electromagnetic compatibility (EMC) is an important stage in the design of modern radio-electronic equipment (REE). One of the purposes of the EMC is protection against conductive electromagnetic interference (EMI) penetrating the REE directly through the conductors [1]. Among this interference, electrostatic discharge (ESD) should be singled out, which under certain conditions can become conducted interference. The main sources of ESD accumulation and transfer are humans, charged dielectrics, and insulated metal parts. Currently, three main forms of current have been standardized to study the immunity to the ESD impact: a human body model (HBM) [2], a mechanical model [3], and a model of a charged device [4]. In addition, other models describing ESD current forms are being developed, for example, a model of a charged printed circuit board [5] and a model of a charged cable [6–8]. There are many circuit engineering models that implement the forms of the ESD current pulses. These models allow calculating currents and voltages in the REE circuit analysis [9–16]. In general, ESD can lead to partial or complete failure of REE, as well as to the interruption of its functioning. Therefore, it is necessary to apply effective measures that protect REE against ESD. However, despite the danger of ESD, it is not always possible to provide effective protection against it [17–19]. Thus, ESD is known to be one of the frequent causes of failure and loss of spacecraft [20]. It is also known that the probability of failure of integrated circuits (IC) that are in contact with an ESD source is about 0.619 [21]. This high value indicates a low resistance of the IC to the destructive effects of external discharges. The danger of ESD exposure on REE is worsened by the fact that traditional protection devices have a number of shortcomings [1], in particular, insufficient speed and low power. Therefore, it is necessary to search and investigate new protection devices that are devoid of imperfections of traditional ones.

One such solution is a device based on adaptive dielectric thin-film transistors [22]. Their advantage is the possibility of ESD shunting at low leakage currents during normal operation. Another solution is to use materials that can transition from a non-conducting state to a conducting one. For example, a switch based on vanadium dioxide can provide bidirectional ESD protection with an amplitude from 1 to 15 kV [23]. Yet another solution is an approach based on the decomposition of an interference pulse into a sequence of pulses of smaller amplitudes, known as modal

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filtering [24]. This approach may not require a dedicated protection device but relies on the conductors available on the printed circuit boards. Devices using this approach are called modal filters (MF). Similar to MFs are protective meander lines (MLs) [25]. The use of ML for interference decomposition has a number of advantages over MFs: a 2× shorter structure length, a larger number of decomposition pulses due to the presence of cross talk (when comparing the cross sections of two-conductor MLs and MFs), the possibility of the absence of a dielectric. It is also important to mention the study of the decomposition of the ESD peak emission by HBM in the meander MSL [26]. Due to this decomposition, its attenuation was up to 1.44, 1.3, and 4.6 times at distances between conductors (s) of 50, 150, and 1 μm , respectively. Thus, to ensure maximum ESD attenuation in a meander MSL, a strong coupling between the conductors is required. This coupling in the structure of a meander MSL is achieved because of a small s . However, this also makes it difficult to implement such a device in practice. Therefore, a more promising structure has been investigated, an ML with a broadside coupling [27], which allows the ESD attenuation of up to 1.61 times. In such a structure, the coupling between the conductors depends on the thickness of the dielectric substrate.

In addition, when analyzing the ESD impact on signal conductors, it is also important to measure its cross talk on passive conductors. Thus, a number of studies have estimated the influence of grounding methods and the width of the protective path in coupled lines on the amplitude of cross talk [28, 29]. It was revealed that an increase in the width of the protective path by two and three times can lead to a decrease in the amplitude of the cross talk by 1.2 and 1.5 times. Moreover, the cross talk at the far end can be reduced by 1.5 times with a certain connection of the protective path. Reducing cross talk is an urgent task of REE EMC. Therefore, the purpose of this work is to investigate the possibility of reducing cross talk from ESD using an ML with broadside coupling.

II. INITIAL DATA

For this study, we chose an MSL consisting of active and passive conductors that are located parallel to each other and connected to a path with $Z=50 \Omega$. The cross section and circuit diagram of this MSL are shown in Fig. 1 (hereinafter, for simplicity, we will call it structure 1). Here and further on the circuit diagrams, we mark only the nodes in which the response will be calculated. The cross-sectional parameters were chosen so that $(Z_e Z_o)^{0.5} = 50 \Omega$: the width and thickness of the conductors $w = 726 \mu\text{m}$ and $t = 18 \mu\text{m}$, the thickness of the substrate $h = 500 \mu\text{m}$, and the dielectric constant of the substrate

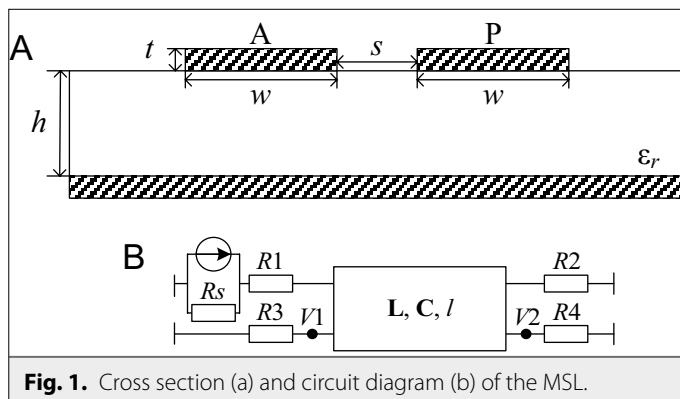


Fig. 1. Cross section (a) and circuit diagram (b) of the MSL.

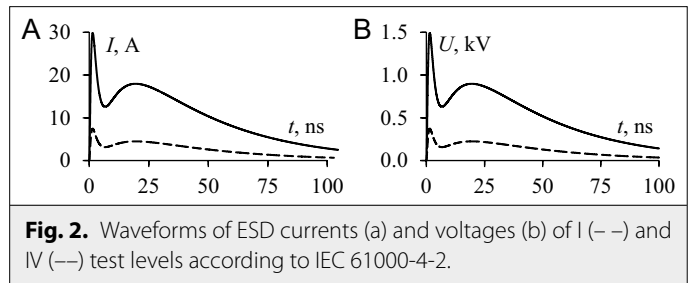


Fig. 2. Waveforms of ESD currents (a) and voltages (b) of I (—) and IV (---) test levels according to IEC 61000-4-2.

$\epsilon_r = 4.5$. The length of the line was $l=100 \text{ mm}$. Resistances on the diagram were $R1=R2=R3=R4=50 \Omega$. The ESD source is presented by a current source connected in parallel with a resistor $R_s = 1 \text{ M}\Omega$. As an excitation, we took the ESD form according to the HBM, corresponding to the I and IV degrees of hardness, according to IEC 61000-4-2 [30]. Further, for simplicity, we will call them ESD 1 and ESD 4. Their current and voltage waveforms are shown in Fig. 2. Note that further evaluation will be performed on the example of the ESD voltage form.

III. MAIN RESULTS

First, we evaluated the effect of s on the amplitude of cross talk from ESD at the near (NEXT) and far (FEXT) ends at nodes V1 and V2 in Fig. 1, respectively. Fig. 3 shows the responses in node V1 and Fig. 4—in node V2 at $s = 100, 550, \text{ and } 1000 \mu\text{m}$, obtained in Keysight advanced design system (ADS) and analytically [31] under the excitation from Fig. 2.

Figs. 3 and 4 demonstrate that the simulation results almost completely match the analytical calculations. The maximum root-mean-square error is 17% (Fig. 4B). With ESD 4, the maximum amplitudes of NEXT and FEXT were 249.62 and 68.13 V, 86.20 and 49.75 V, and 45.19 and 36.18 V for $s = 100, 550, 1000 \mu\text{m}$, respectively. With ESD 1, they were 62.40 and 17.03 V, 21.55 and 12.44 V, and 11.30 and 9.04

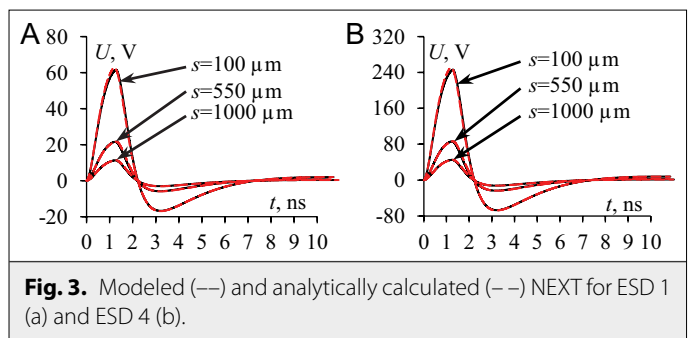


Fig. 3. Modeled (—) and analytically calculated (---) NEXT for ESD 1 (a) and ESD 4 (b).

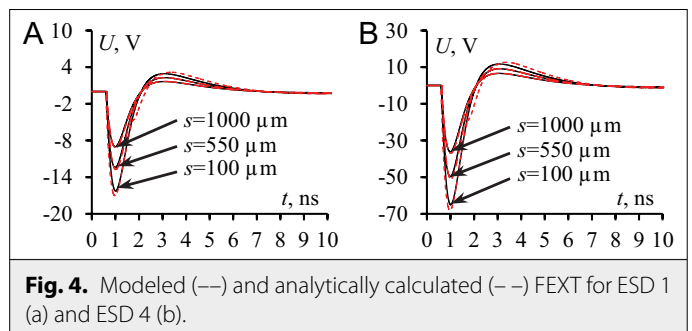
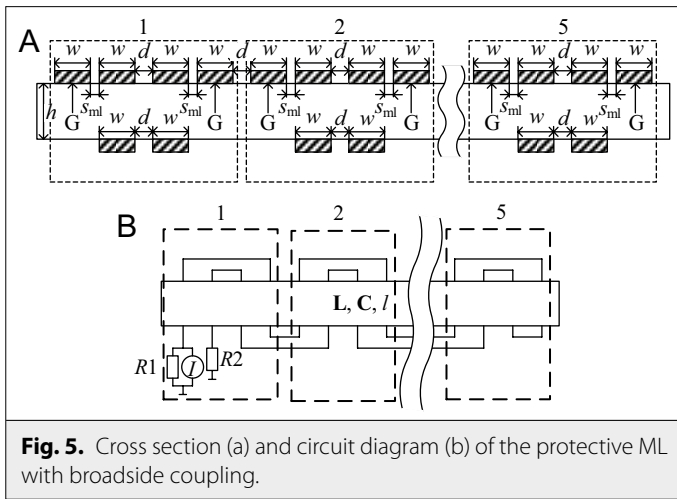


Fig. 4. Modeled (—) and analytically calculated (---) FEXT for ESD 1 (a) and ESD 4 (b).



V for $s = 100, 550,$ and $1000 \mu\text{m}$, respectively. The amplitudes of the cross talk from the signals in Fig. 2B, for NEXT and FEXT, are 16.73% and 4.57%, 5.78% and 3.33%, and 3.03% and 2.42% for $s = 100, 550,$ and $1000 \mu\text{m}$, respectively.

Second, we considered the possibility of reducing cross talk by using a protective ML with broadside coupling. For this purpose, a model of the ML with broadside coupling was created based on its S-parameters measured experimentally [27]. Fig. 5 shows a cross section and connection diagram of a protective ML with a broadside coupling.

Prior to experimental measurements, the topology of the ML layout with broadside coupling was developed using the following parameters obtained in the optimization phase: $w=7.5 \text{ mm}, t=18 \mu\text{m}, d=3w, s_{ml}=5.5 \text{ mm}, h=1.5 \text{ mm}$ and $\epsilon_r=4$. We used SMA connectors manufactured by Molex with an operating frequency of 18 GHz and a wave impedance of 50 Ohms. The printed circuit board (PCB) with the ML layout was manufactured by “Elektroconnect” Ltd. in Novosibirsk. Fig. 6 shows the PCB with the ML layout with broadside coupling.

Note that the PCB with ML and a broadside coupling layout in Fig. 6 is designed to operate in DC circuits with a current of 2.31 A and a voltage of 1.1 kV. Therefore, its dimensions can be significantly reduced for operation in lower current and voltage, AC, or signal circuits. This

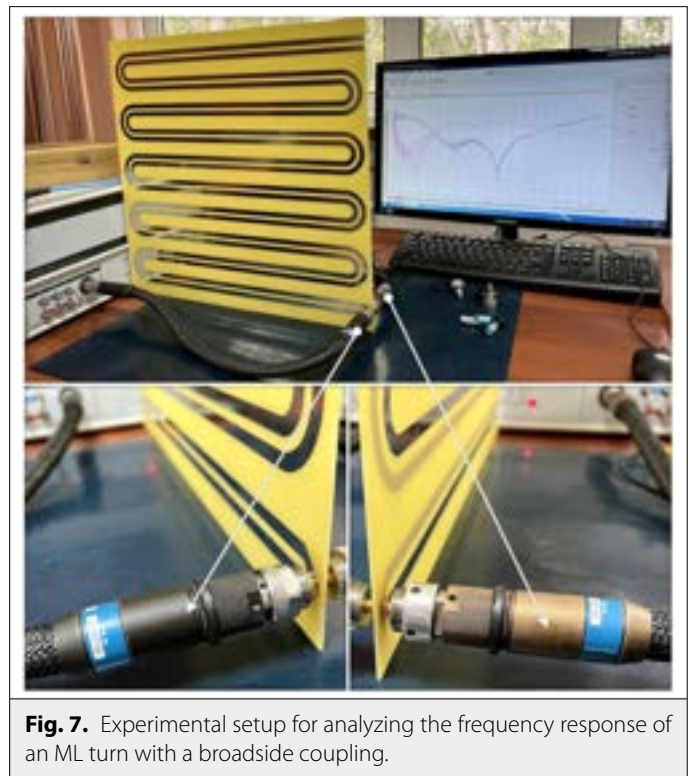
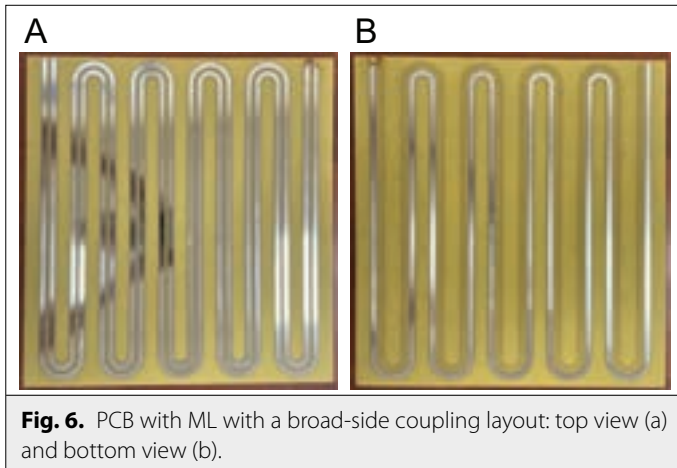


Fig. 7. Experimental setup for analyzing the frequency response of an ML turn with a broadside coupling.

can be achieved by optimizing the geometric parameters according to the relevant criteria while maintaining the protective properties. After the PCB with the ML layout was manufactured, its S-parameters were measured using the R4M-18 vector circuit analyzer manufactured by “Mikran” JSC. For this purpose, the PCB with the ML layout was connected to the analyzer using ultra-high frequency phase-stable cables. The frequency response was analyzed in the range from 10 MHz to 5 GHz. A two-port SOLT calibration was performed prior to the measurements. The experimental setup for the frequency response analysis is shown in Fig. 7

Two configurations were studied: with the ML at the input of the active conductor of the MSL and with the ML at both ends of its passive conductor (hereinafter, for simplicity, we will call them structures 2 and 3, respectively). The measurements were made when the lines were matched, at $s = 1000 \mu\text{m}$ and $s = 100 \mu\text{m}$, and with the second excitation from Fig. 2. Fig. 8 shows the circuit diagrams of structures

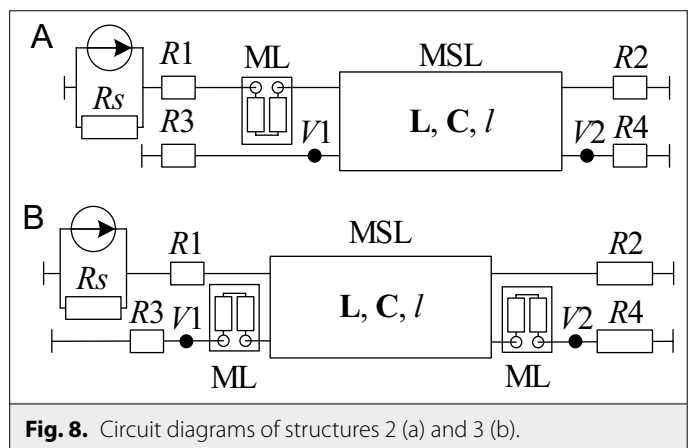


Fig. 8. Circuit diagrams of structures 2 (a) and 3 (b).

2 and 3, where ML is the ML with broadside coupling (Fig. 5) with S -parameters measured on the experimental setup from Fig. 7 The MSL cross sections in structures 2 and 3 are the same as in Fig. 1A, and the ML cross sections are the same as in Fig. 5A.

Comparison of the obtained time responses in nodes $V1$ and $V2$ of the MSL without the ML and with it is shown in Fig. 9. They were calculated in ADS based on the experimentally measured S -parameters of the ML with a broad-side coupling (setup in Fig.7) and the MSL model built in ADS.

Figs. 9 and 10 show that in structure 2, the maximum amplitudes of NEXT and FEXT do not exceed 29.67 and 23.35 V when $s = 1000 \mu\text{m}$ and 163.45 and 43.94 V when $s = 100 \mu\text{m}$, respectively. In structure 3, these values are 28.1 and 21.75 V, and 155.53 and 39.64 V, respectively. Thus, in structure 2, NEXT and FEXT were reduced by 34% and 36% when $s = 100$ and $1000 \mu\text{m}$, respectively, and in structure 3 by 38% and 40% when $s = 100$ and $1000 \mu\text{m}$. Since structure 2 is simpler than structure 3, it is the most promising for practical application. Moreover, the active line is additionally protected in structure 2 [27].

A high voltage amplitude of the ESD can lead to an electrical breakdown, a fast rise time—to sparking, the average effective voltage value—to component burnout, etc. Therefore, as a third step, we evaluated the probability of occurrence of these factors by analyzing the N -norms of structures 1–3 [32]. Table I shows the names, equations, and applications of each norm.

Since the character of changes in N -norms will be the same for both effects from Fig. 2, they were calculated only for ESD 4. Figs. 11, 12, and 13 show the calculated N -norms in nodes $V1$ and $V2$ of all three structures with a change in s in the range of 50–1000 μm with a step of 50 μm .

In Fig. 11 for structure 1, it can be seen that increasing s reduces the values of all norms in node $V1$, which reduces the risks associated

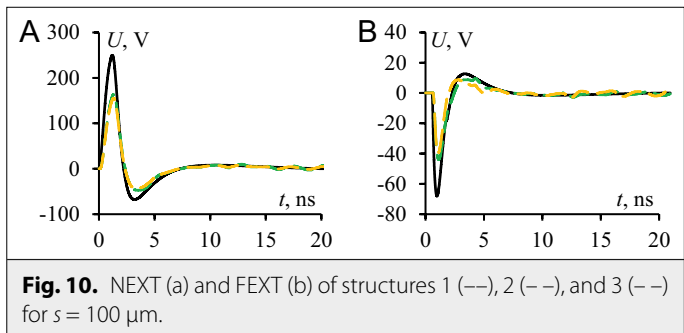
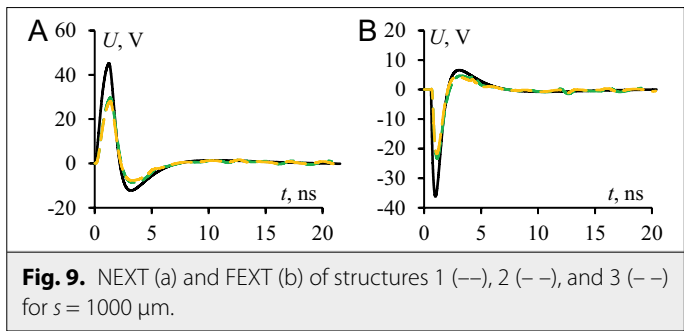


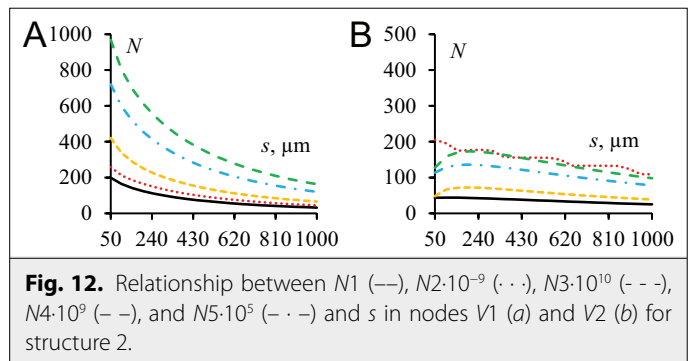
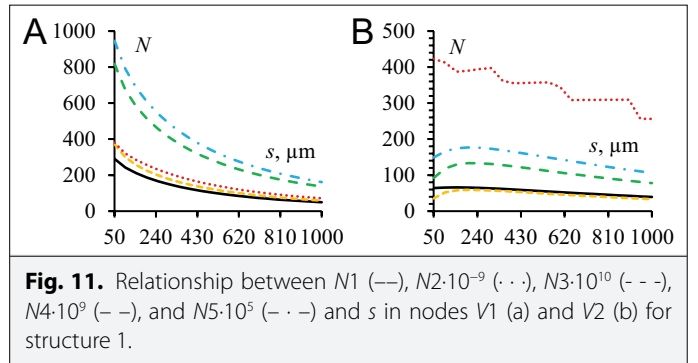
TABLE I. N -NORMS DESCRIPTIONS AND APPLICATIONS

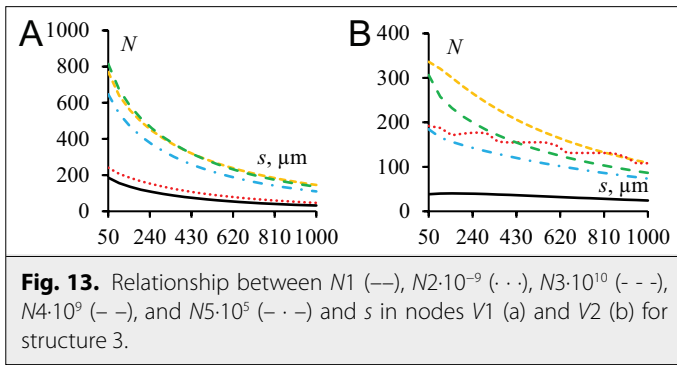
Norm Equation	Name	Application
$N1 = R(t) _{\text{max}}$	Peak (absolute) value	Circuit upset/electric breakdown/arc-over effects
$N2 = \left \frac{\partial R(t)}{\partial t} \right _{\text{max}}$	Peak (absolute) derivative	Component arcing / circuit upset
$N3 = \left \int_0^t R(t) dt \right _{\text{max}}$	Peak (absolute) impulse	Dielectric puncture (if R denotes E field)
$N4 = \int_0^{\infty} R(t) dt$	Rectified total impulse	Equipment damage
$N5 = \left\{ \int_0^{\infty} R(t) ^2 dt \right\}^{\frac{1}{2}}$	Square root of action integral	Component burnout

with them. In the $V2$ node, the norms increase with increasing s up to 150 μm and then decrease monotonously. It is important to note that $N2$ has a stepped character.

When $s = 1000 \mu\text{m}$ in nodes $V1$ and $V2$ of structure 1, the norms decreased (relative to the norms of structure 1 when $s = 50 \mu\text{m}$) by the following values: $N1$ —83% and 38%, $N2$ —81% and 39%, $N3$ —84% and 5%, $N4$ —83% and 15%, $N5$ —83% and 29%, respectively.

Figs. 12 and 13 show that the nature of changes in norms with an increase in s is similar to Fig. 11. When $s = 1000 \mu\text{m}$ in nodes $V1$ and





V2 of structure 2, the norms decreased (relative to the norms of structure 2 when $s = 50 \mu\text{m}$) as follows: $N1$ by 84% and 42%, $N2$ by 83% and 47%, $N3$ by 84% and 20%, $N4$ by 83% and 23%, and $N5$ by 83% and 31%, respectively. Similarly, in structure 3, the decreases were as follows: $N1$ by 83% and 37%, $N2$ by 81% and 44%, $N3$ by 81% and 68%, $N4$ by 83% and 72%, and $N5$ by 83% and 60%, respectively.

For clarity, Table II summarizes the average values of the norms for all the considered cases and their changes (Δ) relative to the case in Fig. 1 (where the signs “-” and “+” mean a decrease and an increase, respectively).

Table II shows that $N1$, $N2$, and $N5$ in structures 2 and 3 decreased, and the maximum difference between the average values of these norms was 7%. Meanwhile, $N3$ and $N4$ increased in both structures. Thus, an increase in these norms in nodes V1 and V2 of structure 2 is no more than 19% and 28%, and in structure 3 127% and 325%, respectively. Therefore, structure 2 is the most effective for suppressing ESD cross talk.

IV. CONCLUSIONS

The study demonstrated the possibility of attenuating NEXT and FEXT in a coupled MSL. Additionally, the cross talk was estimated in this structure by means of quasi-static modeling and analytical calculations. The study also demonstrated that NEXT and FEXT can be attenuated using a protective ML with broadside coupling. In this

TABLE II. AVERAGE N -NORMS COMPARISON

V1					
Structure	$N1$ ($\Delta 1$)	$N2$ ($\Delta 2$)	$N3$ ($\Delta 3$)	$N4$ ($\Delta 4$)	$N5$ ($\Delta 5$)
1	120	167	145	332	392
2	80 (-34%)	107 (-36%)	163 (+12%)	397 (+19%)	294 (-25%)
3	77 (-36%)	108 (-35%)	329 (+127%)	332 (0%)	268 (-32%)
V2					
Structure	$N1$ ($\Delta 1$)	$N2$ ($\Delta 2$)	$N3$ ($\Delta 3$)	$N4$ ($\Delta 4$)	$N5$ ($\Delta 5$)
1	55	345	47	108	147
2	35 (-35%)	152 (-56%)	56 (+20%)	139 (+28%)	110 (-25%)
3	33 (-39%)	150 (-57%)	199 (+325%)	155 (+43%)	115 (-21%)

case, the level of NEXT and FEXT does not exceed 2% and 1.5% of half of the e.m.f. when $s = 1000 \mu\text{m}$, and 10% and 3% when $s = 100 \mu\text{m}$, respectively. The maximum NEXT and FEXT attenuations were 1.6 and 1.7 times, respectively.

According to the IEC 61000-4-25 [33] standard, the attenuation of cross talk should be at least 20 dB. In this study, its level is not more than 10% of the voltage in Fig. 2B. In the line with $s = 1000 \mu\text{m}$, even without protection, the level of cross talk does not exceed 3% of half of the e.m.f. However, when $s = 100 \mu\text{m}$, NEXT is 16.73% of half of the e.m.f. level in a two-wire MSL without a protective ML, and when using a protective ML 10%. As a result, the ML with a broadside coupling can be used both to protect against dangerous conducted interference and to protect against high levels of cross talk. This is especially important considering the trends toward the miniaturization of printed circuit boards and an increase in the density of components on them. For example, the use of the proposed method of protection will completely eliminate the threat of cross talk from ESD 1 in the CAN bus for chips manufactured by Texas Instruments HVDA55x-Q1 series [34], as well as significantly reduce the risk of damage to this component because of ESD 4. In addition, the proposed device will also weaken the voltage of the ESD when it passes through the active conductor.

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